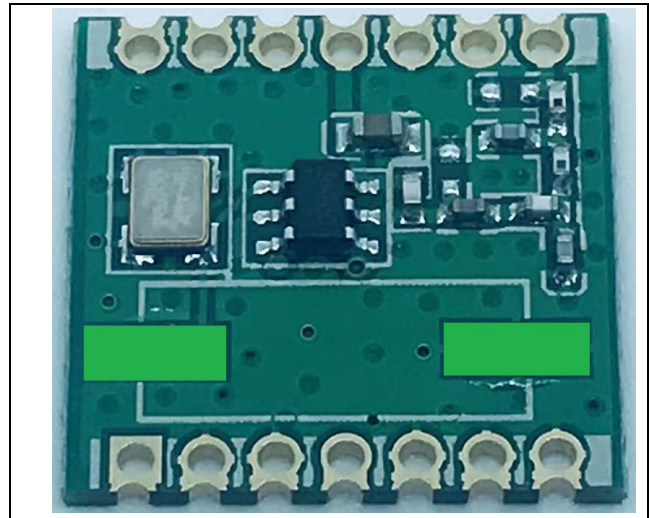


Features

- Embedded EEPROM
 - Very Easy Development with RFPDK
 - All Features Programmable
- Frequency Range: 240 to 960 MHz
- FSK, GFSK and OOK Modulation
- Symbol Rate:
 - 0.5 to 100 ksps (FSK/GFSK)
 - 0.5 to 30 ksps (OOK)
- Deviation: 1.0 to 200 kHz
- Two-wire Interface for Registers Accessing and EEPROM Programming
- Output Power: -10 to +13 dBm
- Supply Voltage: 1.8 to 3.6 V
- Sleep Current: < 20 nA
- FCC/ETSI Compliant
- RoHS Compliant
- Module Size: 17.8*12.8*2.3mm (YTX119)
16*16*2.3mm (YTX119S)



YTX119S

Descriptions

The YTX119/S is a high performance, highly flexible, low-cost, single-chip (G)FSK/OOK transmitter for various, 240 to 960 MHz wireless applications. It is a part of the HOPERF NextGenRF™ family, which includes a complete line of transmitters, receivers and transceivers. The YTX119/S provides the simplest way to control the data transmission. The transmission is started when an effective level turnover is detected on the DATA pin, while the transmission action will stop after the DATA pin holding level low for a defined time window, or after a two-wire interface (TWI) command is issued. The chip features can be configured in two different ways: setting the configuration registers through the TWI, or programming the embedded RFPDK. The device operates from a supply voltage of 1.8 V to 3.6 V, consumes 27.6 mA (FSK @ 868.35 MHz) when transmitting +10 dBm output power, and only leak 20 nA when it is in sleep state. The YTX119/S transmitter together with the ytx2219A receiver enables a robust RF link.

Applications

- Low-Cost Consumer Electronics Applications
- Home and Building Automation
- Remote Fan Controllers
- Infrared Transmitter Replacements
- Industrial Monitoring and Controls
- Remote Lighting Control
- Wireless Alarm and Security Systems
- Remote Keyless Entry (RKE)

Abbreviations

Abbreviations used in this data sheet are described below

AN	Application Notes	PA	Power Amplifier
BOM	Bill of Materials	PC	Personal Computer
BSC	Basic Spacing between Centers	PCB	Printed Circuit Board
EEPROM	Electrically Erasable Programmable Read-Only Memory	PN	Phase Noise
ESD	Electro-Static Discharge	RCLK	Reference Clock
ESR	Equivalent Series Resistance	RF	Radio Frequency
ETSI	European Telecommunications Standards Institute	RFPDK	RF Product Development Kit
FCC	Federal Communications Commission	RoHS	Restriction of Hazardous Substances
FSK	Frequency Shift Keying	Rx	Receiving, Receiver
GFSK	Gauss Frequency Shift Keying	SOT	Small-Outline Transistor
Max	Maximum	SR	Symbol Rate
MCU	Microcontroller Unit	TWI	Two-wire Interface
Min	Minimum	Tx	Transmission, Transmitter
MOQ	Minimum Order Quantity	Typ	Typical
NP0	Negative-Positive-Zero	USB	Universal Serial Bus
OBW	Occupied Bandwidth	XO/XOSC	Crystal Oscillator
OOK	On-Off Keying	XTAL	Crystal
		PA	Power Amplifier

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1. Electrical Characteristics

$V_{DD} = 3.3\text{ V}$, $T_{OP} = 25\text{ }^{\circ}\text{C}$, $F_{RF} = 868.35\text{ MHz}$, FSK modulation, output power is +10 dBm terminated in a matched 50 Ω impedance, unless otherwise noted.

1.1 Recommended Operating Conditions

Table 2. Recommended Operation Conditions

Parameter	Symbol	Conditions	Min	Typ	Max	Unit
Operation Voltage Supply	V_{DD}		1.8		3.6	V
Operation Temperature	T_{OP}		-40		85	$^{\circ}\text{C}$
Supply Voltage Slew Rate			1			mV/us

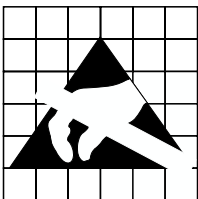
1.2 Absolute Maximum Ratings

Table 3. Absolute Maximum Ratings^[1]

Parameter	Symbol	Conditions	Min	Max	Unit
Supply Voltage	V_{DD}		-0.3	3.6	V
Interface Voltage	V_{IN}		-0.3	$V_{DD} + 0.3$	V
Junction Temperature	T_J		-40	125	$^{\circ}\text{C}$
Storage Temperature	T_{STG}		-50	150	$^{\circ}\text{C}$
Soldering Temperature	T_{SDR}	Lasts at least 30 seconds		255	$^{\circ}\text{C}$
ESD Rating		Human Body Model (HBM)	-2	2	kV
Latch-up Current		@ 85 $^{\circ}\text{C}$	-100	100	mA

Note:

[1]. Stresses above those listed as “absolute maximum ratings” may cause permanent damage to the device. This is a stress rating only and functional operation of the device under these conditions is not implied. Exposure to maximum rating conditions for extended periods may affect device reliability.



Caution! ESD sensitive device. Precaution should be used when handling the device in order to prevent permanent damage.

1.3 Transmitter Specifications

Table 4. Transmitter Specifications

Parameter	Symbol	Conditions	Min	Typ	Max	Unit
Frequency Range ^[1]	F_{RF}		240		960	MHz
Synthesizer Frequency Resolution	F_{RES}	$F_{RF} \leq 480$ MHz		198		Hz
		$F_{RF} > 480$ MHz		397		Hz
Symbol Rate	SR	FSK/GFSK	0.5		100	ksps
		OOK	0.5		30	ksps
(G)FSK Modulation Deviation Range	F_{DEV}		1		200	kHz
Bandwidth-Time Product	BT	GFSK modulation	-	0.5	-	-
Maximum Output Power	$P_{OUT(Max)}$			+13		dBm
Minimum Output Power	$P_{OUT(Min)}$			-10		dBm
Output Power Step Size	P_{STEP}			1		dB
OOK PA Ramping Time ^[2]	t_{RAMP}		0		1024	us
Current Consumption @ 433.92 MHz	$I_{DD-433.92}$	OOK, 0 dBm, 50% duty cycle		6.7		mA
		OOK, +10 dBm, 50% duty cycle		13.4		mA
		OOK, +13 dBm, 50% duty cycle		17.4		mA
		FSK, 0 dBm, 9.6 ksps		10.5		mA
		FSK, +10 dBm, 9.6 ksps		23.5		mA
		FSK, +13 dBm, 9.6 ksps		32.5		mA
Current Consumption @ 868.35 MHz	$I_{DD-868.35}$	OOK, 0 dBm, 50% duty cycle		8.0		mA
		OOK, +10 dBm, 50% duty cycle		15.5		mA
		OOK, +13 dBm, 50% duty cycle		19.9		mA
		FSK, 0 dBm, 9.6 ksps		12.3		mA
		FSK, +10 dBm, 9.6 ksps		27.6		mA
		FSK, +13 dBm, 9.6 ksps		36.1		mA
Sleep Current	I_{SLEEP}			20		nA
Frequency Tune Time	t_{TUNE}			370		us
Phase Noise @ 433.92 MHz	PN _{433.92}	100 kHz offset from F_{RF}		-80		dBc/Hz
		600 kHz offset from F_{RF}		-98		dBc/Hz
		1.2 MHz offset from F_{RF}		-107		dBc/Hz
Phase Noise @ 868.35 MHz	PN _{868.35}	100 kHz offset from F_{RF}		-74		dBc/Hz
		600 kHz offset from F_{RF}		-92		dBc/Hz
		1.2 MHz offset from F_{RF}		-101		dBc/Hz
Harmonics Output for 433.92 MHz ^[3]	H2 _{433.92}	2 nd harm @ 867.84 MHz, +13 dBm P _{OUT}		-52		dBm
	H3 _{433.92}	3 rd harm @ 1301.76 MHz, +13 dBm P _{OUT}		-60		dBm
Harmonics Output for 868.35 MHz ^[3]	H2 _{868.35}	2 nd harm @ 1736.7 MHz, +13 dBm P _{OUT}		-67		dBm
	H3 _{868.35}	3 rd harm @ 2605.05 MHz, +13 dBm P _{OUT}		-55		dBm
OOK Extinction Ratio				60		dB

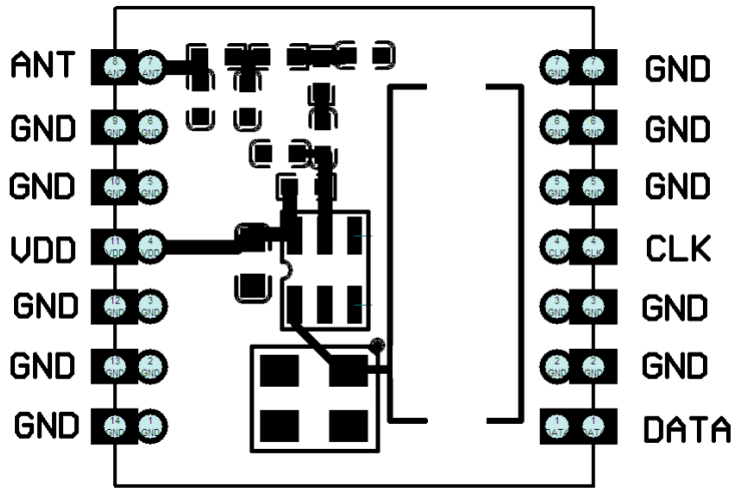
Notes:

[1]. The frequency range is continuous over the specified range.

[2]. 0 and 2ⁿ us, n = 0 to 10, when set to "0", the PA output power will ramp to its configured value in the shortest possible time.

[3]. The harmonics output is measured with the application shown as Figure 10.

2. Pin Descriptions



YTX119S. Pin Diagram

Table 6. YTX119/S Pin Descriptions

Pin Number		Name	I/O	Descriptions
YTX119	YTX119S			
1	1	ANT	O	Transmitter RF Output
2	4	VDD	I	Power Supply 1.8V to 3.6V
3	8	DATA	I/O	Data input to be transmitted or Data pin to access the embedded EEPROM
4	2,7,9,14	GND	I	Ground
5	3,5,6,	NC	---	Connect to GND
6	11	CLK	I	Clock pin to access the embedded EEPROM
7		GND	I	Ground
8	10,12,13	NC	---	Connect to GND

3. Typical Performance Characteristics

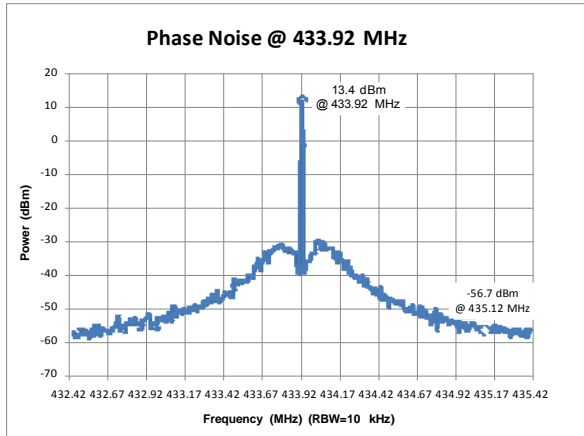


Figure 3. Phase Noise, $F_{RF} = 433.92$ MHz,
 $P_{OUT} = +13$ dBm, Unmodulated

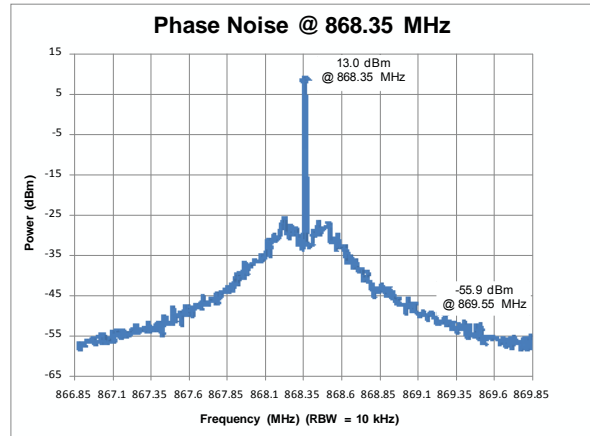


Figure 4. Phase Noise, $F_{RF} = 868.35$ MHz,
 $P_{OUT} = +13$ dBm, Unmodulated

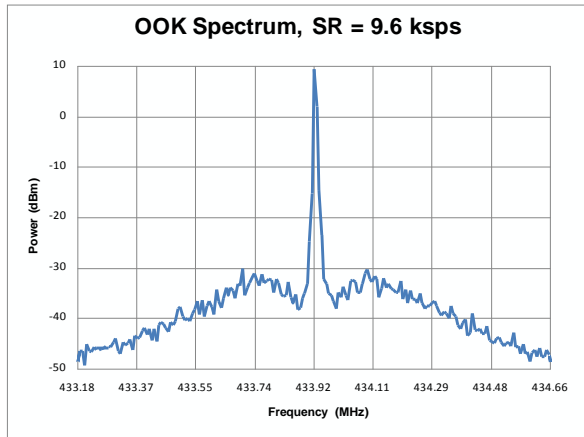


Figure 5. OOK Spectrum, SR = 9.6 kbps,
 $P_{OUT} = +10$ dBm, $t_{RAMP} = 32$ us

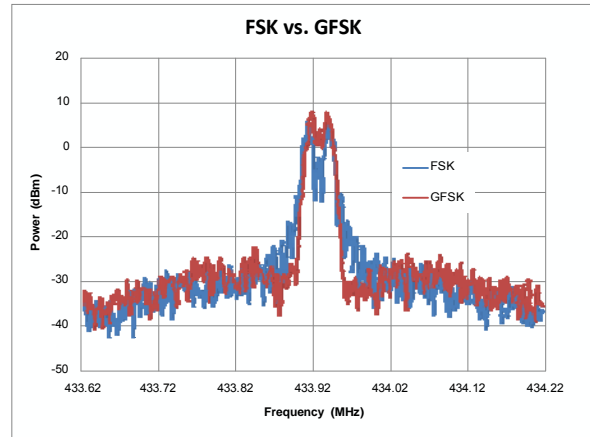


Figure 6. FSK/GFSK Spectrum,
SR = 9.6 kbps, $F_{DEV} = 15$ kHz

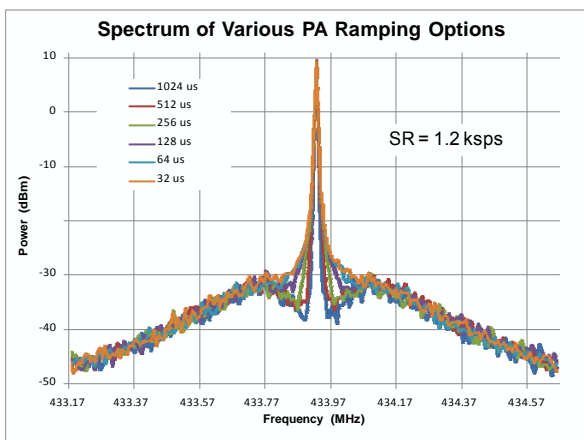


Figure 7. Spectrum of PA Ramping,
SR = 1.2 kbps, $P_{OUT} = +10$ dBm

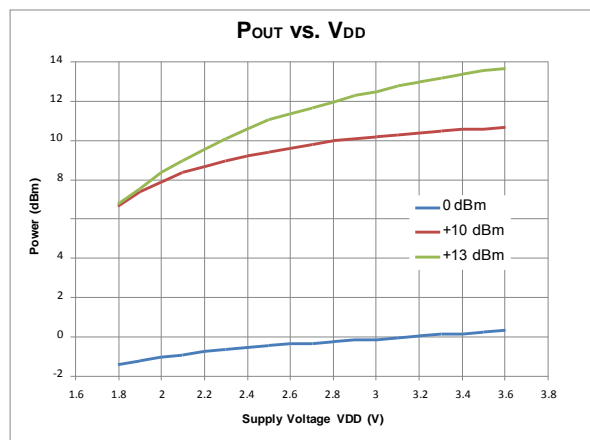
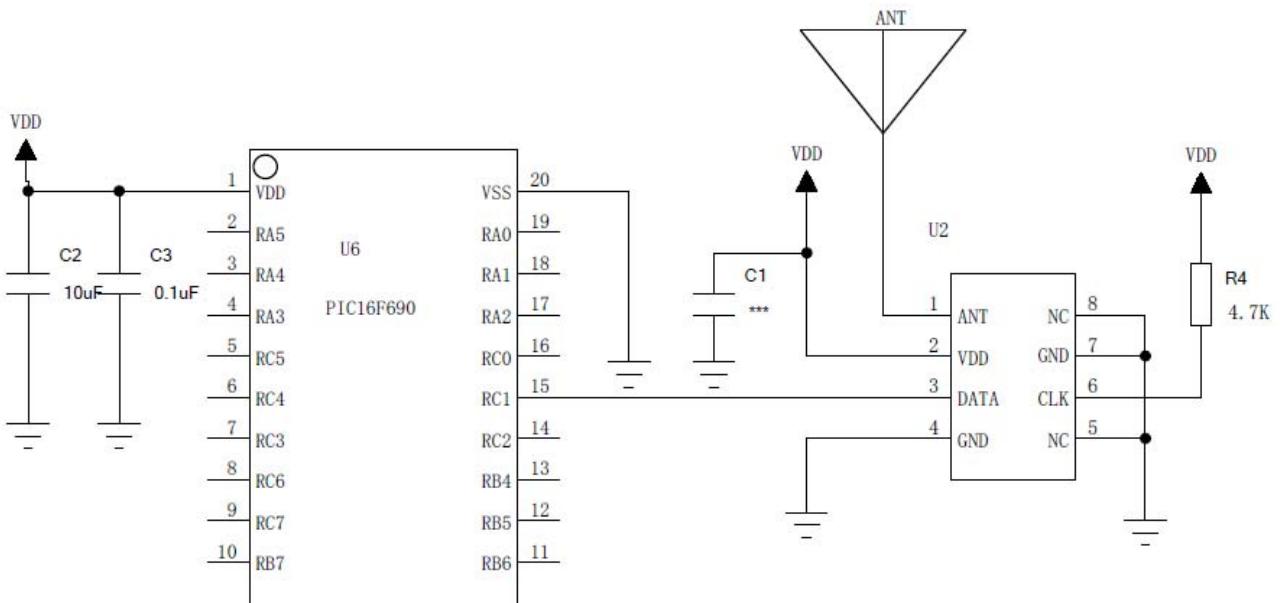
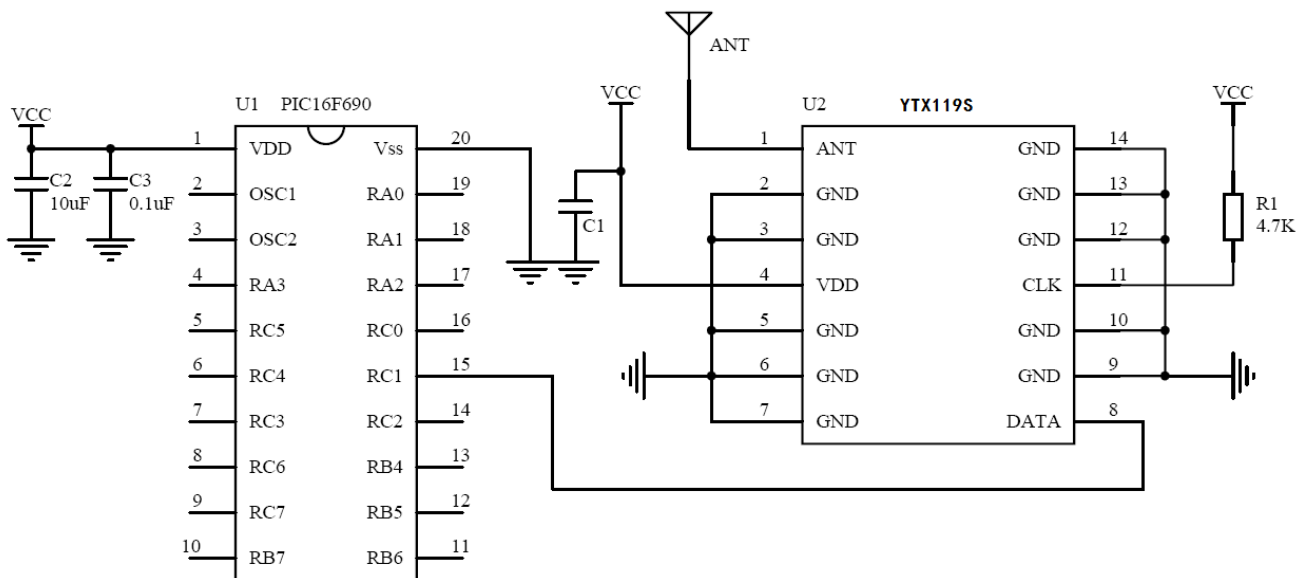


Figure 8. Output Power vs. Supply Voltages, $F_{RF} = 433.92$ MHz

4. Typical Application Schematics



YTX119



YTX119S

Figure 9: Typical Application Schematic

5. Functional Descriptions

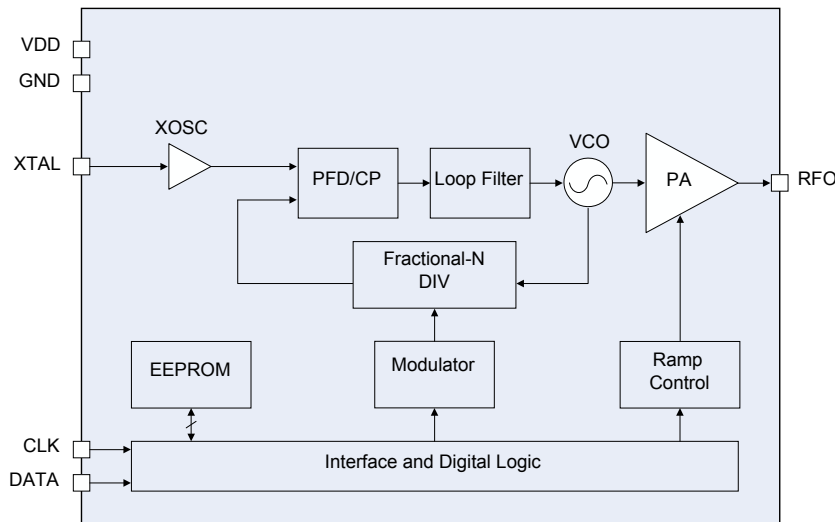


Figure 11. YTX119/S Functional Block Diagram

5.1 Overview

The YTX119/S is a high performance, highly flexible, low-cost, single-chip (G)FSK/OOK transmitter for various 240 to 960 MHz wireless applications. It is part of the HOPERF NextGenRF™ family, which includes a complete line of transmitters, receivers and transceivers. The chip is optimized for the low system cost, low power consumption, battery powered application with its highly integrated and low power design.

The functional block diagram of the YTX119/S is shown in the figure above. The YTX119/S is based on direct synthesis of the RF frequency, and the frequency is generated by a low-noise fractional-N frequency synthesizer. It uses a 1-pin crystal oscillator circuit with the required crystal load capacitance integrated on-chip to minimize the number of external components. Every analog block is calibrated on each Power-on Reset (POR) to the internal voltage reference. The calibration can help the chip to finely work under different temperatures and supply voltages. The YTX119/S uses the DATA pin for the host MCU to send in the data. The input data will be modulated and sent out by a highly efficient PA, which output power can be configured from -10 to +13 dBm in 1 dB step size

The user can directly use the YTX119/S default configuration for immediate demands. If that cannot meet the system requirement, on-line register configuration and off-line EEPROM programming configuration are available for the user to customize the chip features. The on-line configuration means there is an MCU available in the application to configure the chip registers through the 2-wire interface, while the off-line configuration is done by the HOPERF USB Programmer and the RFPDK. After the configuration is done, only the DATA pin is required for the host MCU to send in the data and control the transmission. The YTX119/S operates from 1.8 to 3.6 V so that it can finely work with most batteries to their useful power limits. It only consumes 15.5 mA (OOK @ 868.35 MHz) / 27.6 mA (FSK @ 868.35 MHz) when transmitting +10 dBm power under 3.3 V supply voltage.

5.2 Modulation, Frequency, Deviation and Symbol Rate

The YTX119/S supports GFSK/FSK modulation with the symbol rate up to 100 kbps, as well as OOK modulation with the symbol rate up to 30 kbps. The supported deviation of the (G)FSK modulation ranges from 1 to 200 kHz. The YTX119/S continuously covers the frequency range from 240 to 960 MHz, including the license free ISM frequency band around 315 MHz, 433.92 MHz, 868.35 MHz and 915 MHz. The device contains a high spectrum purity low power fractional-N frequency synthesizer with output frequency resolution better than 198 Hz when the frequency is less than 480 MHz, and is about 397 Hz

when the frequency is larger than 480 MHz. See the table below for the modulation, frequency and symbol rate specifications.

Table 9. Modulation, Frequency and Symbol Rate

Parameter	Value	Unit
Modulation	(G)FSK/OOK	-
Frequency	240 to 960	MHz
Deviation	1 to 200	kHz
Frequency Resolution ($F_{RF} \leq 480$ MHz)	198	Hz
Frequency Resolution ($F_{RF} > 480$ MHz)	397	Hz
Symbol Rate (FSK/GFSK)	0.5 to 100	ksps
Symbol Rate (OOK)	0.5 to 30	ksps

5.3 Embedded EEPROM and RFPDK

The RFPDK (RF Products Development Kit) is a very user-friendly software tool delivered for the user configuring the YTX119/S in the most intuitional way. The user only needs to fill in/select the proper value of each parameter and click the “Burn” button to complete the chip configuration. See the figure below for the accessing of the EEPROM and Table 10 for the summary of all the configurable parameters of the YTX119/S in the RFPDK.

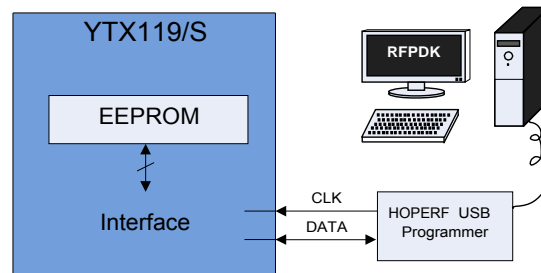


Figure 12. Accessing Embedded EEPROM

For more details of the HOPERF USB Programmer and the RFPDK, please refer to “AN103 ytx211xA-221xA One-Way RF Link Development Kits Users Guide”. For the detail of YTX119/S configurations with the RFPDK, please refer to “AN122 ytx2113/19A Configuration Guideline”.

Table 10. Configurable Parameters in RFPDK

Category	Parameters	Descriptions	Default	Mode
RF Settings	Frequency	To input a desired transmitting radio frequency in the range from 240 to 960 MHz. The step size is 0.001 MHz.	868.35 MHz	Basic Advanced
	Modulation	The option is FSK or GFSK and OOK.	FSK	Basic Advanced
	Deviation	The FSK frequency deviation. The range is from 1 to 100 kHz.	35 kHz	Basic Advanced
	Symbol Rate	The GFSK symbol rate. The user does not need to specify symbol rate for FSK and OOK modulation.	2.4 ksp/s	Basic Advanced
	Tx Power	To select a proper transmitting output power from -10 dBm to +14 dBm, 1 dB margin is given above +13 dBm.	+13 dBm	Basic Advanced
	Xtal Load	On-chip XOSC load capacitance options: from 10 to 22 pF. The step size is 0.33 pF.	15 pF	Basic Advanced
	Data Representation	To select whether the frequency "Fo + Fdev" represent data 0 or 1. The options are: 0: F-high 1: F-low, or 0: F-low 1: F-high.	0: F-low 1: F-high	Advanced
	PA Ramping	To control PA output power ramp up/down time for OOK transmission, options are 0 and 2 ⁿ us (n from 0 to 10).	0 us	Advanced
Transmitting Settings	Start by	Start condition of a transmitting cycle, by Data Pin Rising/Falling Edge.	Data Pin Rising Edge	Advanced
	Stop by	Stop condition of a transmitting cycle, by Data Pin Holding Low for 2 to 90 ms.	Data Pin Holding Low for 20 ms	Advanced

5.4 Power Amplifier

A highly efficient single-ended Power Amplifier (PA) is integrated in the YTX119/S to transmit the modulated signal out. Depending on the application, the user can design a matching network for the PA to exhibit optimum efficiency at the desired output power for a wide range of antennas, such as loop or monopole antenna. Typical application schematics and the required BOM are shown in "Chapter 4 Typical Application Schematic". For the schematic, layout guideline and the other detailed information please refer to "AN101 ytx211xA Schematic and PCB Layout Design Guideline".

The output power of the PA can be configured by the user within the range from -10 dBm to +13 dBm in 1 dB step size using the HOPERF USB Programmer and RFPDK.

5.5 PA Ramping

When the PA is switched on or off quickly, its changing input impedance momentarily disturbs the VCO output frequency. This process is called VCO pulling, and it manifests as spectral splatter or spurs in the output spectrum around the desired carrier frequency. By gradually ramping the PA on and off, PA transient spurs are minimized. The YTX119/S has built-in PA ramping configurability with options of 0, 1, 2, 4, 8, 16, 32, 64, 128, 256, 512 and 1024 us, as shown in Figure 13. These options are only available when the modulation type is OOK. When the option is set to “0”, the PA output power will ramp up to its configured value in the shortest possible time. The ramp down time is identical to the ramp up time in the same configuration.

HOPERF recommends that the maximum symbol rate should be no higher than 1/2 of the PA ramping “rate”, as shown in the formula below.

$$SR_{Max} \leq 0.5 * \left(\frac{1}{t_{RAMP}} \right)$$

In which the PA ramping “rate” is given by $(1/t_{RAMP})$. In other words, by knowing the maximum symbol rate in the application, the PA ramping time can be calculated by formula below.

$$t_{RAMP} \leq 0.5 * \left(\frac{1}{SR_{MAX}} \right)$$

The user can select one of the values of the t_{RAMP} in the available options that meet the above requirement. If somehow the t_{RAMP} is set to be longer than “ $0.5 * (1/SR_{MAX})$ ”, it will possibly bring additional challenges to the OOK demodulation of the Rx device. For more detail of calculating t_{RAMP} , please refer to “AN122 ytx2113/19A Configuration Guideline”.

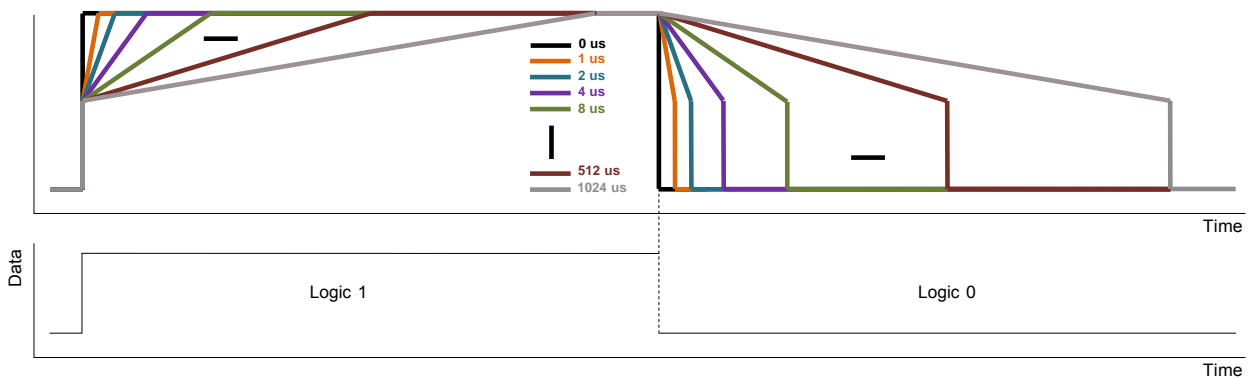


Figure 13. PA Ramping Time

5.6. Working States and Transmission Control Interface

The YTX119/S has following 4 different working states: SLEEP, XO-STARTUP, TUNE and TRANSMIT.

SLEEP

When the YTX119/S is in the SLEEP state, all the internal blocks are turned off and the current consumption is minimized to 20 nA typically.

XO-STARTUP

After detecting a valid control signal on DATA pin, the YTX119/S goes into the XO-STARTUP state, and the internal XO starts to work. The valid control signal can be a rising or falling edge on the DATA pin, which can be configured on the RFPDK. The host MCU has to wait for the t_{XTAL} to allow the XO to get stable. The t_{XTAL} is to a large degree crystal dependent. A typical value of t_{XTAL} is provided in the Table 11.

TUNE

The frequency synthesizer will tune the YTX119/S to the desired frequency in the time t_{TUNE} . The PA can be turned on to transmit the incoming data only after the TUNE state is done, before that the incoming data will not be transmitted. See Figure 16 and Figure 17 for the details.

TRANSMIT

The YTX119/S starts to modulate and transmit the data coming from the DATA pin. The transmission can be ended in 2 methods: firstly, driving the DATA pin low for t_{STOP} time, where the t_{STOP} can be configured from 20 to 90 ms on the RFPDK; secondly, issuing SOFT_RST command over the two-wire interface, this will stop the transmission in 1 ms. See Section 6.2.3 for details of the two-wire interface.

Table 11. Timing in Different Working States

Parameter	Symbol	Min	Typ	Max	Unit
XTAL Startup Time ^[1]	t_{XTAL}		400		us
Time to Tune to Desired Frequency	t_{TUNE}		370		us
Hold Time After Rising Edge	t_{HOLD}	10			ns
Time to Stop the Transmission ^[2]	t_{STOP}	2		90	ms
Notes:					
[1]. This parameter is to a large degree crystal dependent.					
[2]. Configurable from 2 to 9 in 1 ms step size and 20 to 90 ms in 10 ms step size.					

5.6.1 Tx Enabled by DATA Pin Rising Edge

As shown in the figure below, once the YTX119/S detects a rising edge on the DATA pin, it goes into the XO-STARTUP state. The user has to pull the DATA pin high for at least 10 ns (t_{HOLD}) after detecting the rising edge, as well as wait for the sum of t_{XTAL} and t_{TUNE} before sending any useful information (data to be transmitted) into the chip on the DATA pin. The logic state of the DATA pin is “Don't Care” from the end of t_{HOLD} till the end of t_{TUNE} . In the TRANSMIT state, PA sends out the input data after they are modulated. The user has to pull the DATA pin low for t_{STOP} in order to end the transmission.

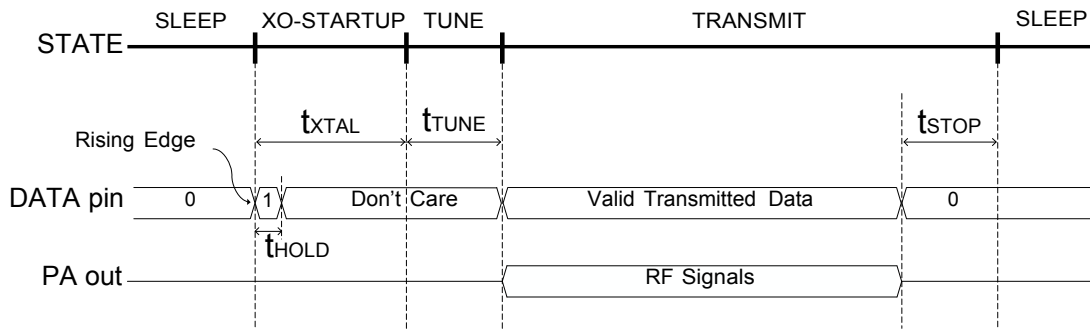


Figure 16. Transmission Enabled by DATA Pin Rising Edge

5.6.2 Tx Enabled by DATA Pin Falling Edge

As shown in the figure below, once the YTX119/S detects a falling edge on the DATA pin, it goes into XO-STARTUP state and the XO starts to work. During the XO-STARTUP state, the DATA pin needs to be pulled low. After the XO is settled, the YTX119/S goes to the TUNE state. The logic state of the DATA pin is “Don't Care” during the TUNE state. In the TRANSMIT state, PA sends out the input data after they are modulated. The user has to pull the DATA pin low for t_{STOP} in order to end the transmission. Before starting the next transmit cycle, the user has to pull the DATA pin back to high.

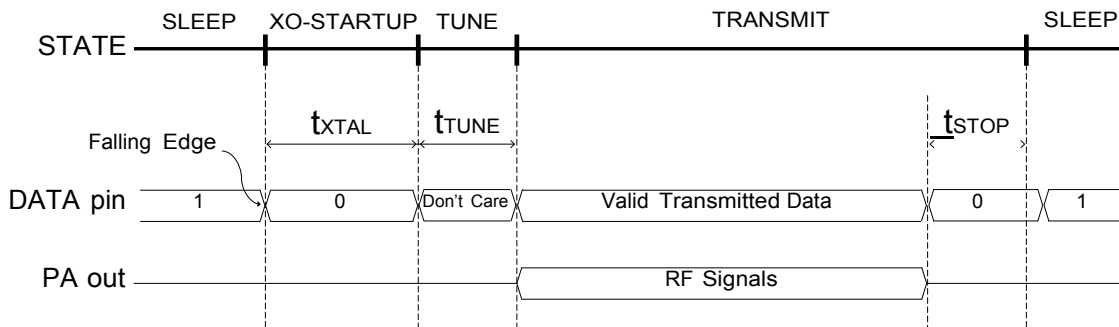


Figure 17. Transmission Enabled by DATA Pin Falling Edge

5.6.3 Two-wire Interface

For power-saving and reliable transmission purposes, the YTX119/S is recommended to communicate with the host MCU over a two-wire interface (TWI): DATA and CLK. The TWI is designed to operate at a maximum of 1 MHz. The timing requirement and data transmission control through the TWI are shown in this section.

Table 12. TWI Requirements

Parameter	Symbol	Conditions	Min	Typ	Max	Unit
Digital Input Level High	V_{IH}		0.8			V_{DD}
Digital Input Level Low	V_{IL}				0.2	V_{DD}
CLK Frequency	F_{CLK}		10		1,000	kHz
CLK High Time	t_{CH}		500			ns
CLK Low Time	t_{CL}		500			ns
CLK Delay Time	t_{CD}	CLK delay time for the first falling edge of the TWI_RST command, see Figure 20	20		15,000	ns
DATA Delay Time	t_{DD}	The data delay time from the last CLK rising edge of the TWI command to the time DATA return to default state			15,000	ns
DATA Setup Time	t_{DS}	From DATA change to CLK falling edge	20			ns
DATA Hold Time	t_{DH}	From CLK falling edge to DATA change	200			ns

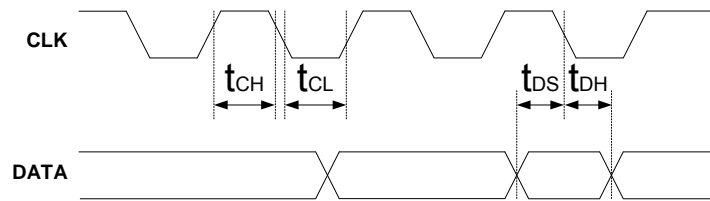


Figure 18. Two-wire Interface Timing Diagram

Once the device is powered up, TWI_RST and SOFT_RST should be issued to make sure the device works in SLEEP state robustly. On every transmission, TWI_RST and TWI_OFF should be issued before the transmission to make sure the TWI circuit functions correctly. TWI_RST and SOFT_RST should be issued again after the transmission for the device going back to SLEEP state reliably till the next transmission. The operation flow with TWI is shown as the figure below.

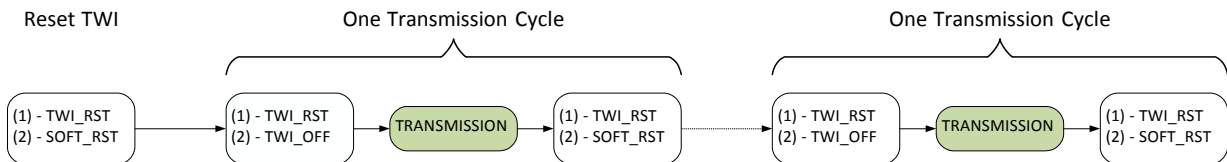


Figure 19. YTX119/S Operation Flow with TWI

Table 13. TWI Commands Descriptions

Command	Descriptions
TWI_RST	<p>Implemented by pulling the DATA pin low for 32 clock cycles and clocking in 0x8D00, 48 clock cycles in total.</p> <p>It only resets the TWI circuit to make sure it functions correctly. The DATA pin cannot detect the Rising/Falling edge to trigger transmission after this command, until the TWI_OFF command is issued.</p> <p>Notes:</p> <ol style="list-style-type: none"> Please ensure the DATA pin is firmly pulled low during the first 32 clock cycles. When the device is configured as Transmission Enabled by DATA Pin Falling Edge, in order to issue the TWI_RST command correctly, the first falling edge of the CLK should be sent t_{CD} after the DATA falling edge, which should be longer than the minimum DATA setup time 20 ns, and shorter than 15 us,

Command	Descriptions
	as shown in Figure 20. 3. When the device is configured as Transmission Enabled by DATA Pin Rising Edge, the default state of the DATA is low, there is no t_{CD} requirement, as shown in Figure 21.
TWI_OFF	Implemented by clocking in 0x8D02, 16 clock cycles in total. It turns off the TWI circuit, and the DATA pin is able to detect the Rising/Falling edge to trigger transmission after this command, till the TWI_RST command is issued. The command is shown as Figure 22.
SOFT_RST	Implemented by clocking in 0xBD01, 16 clock cycles in total. It resets all the other circuits of the chip except the TWI circuit. This command will trigger internal calibration for getting the optimal device performance. After issuing the SOFT_RST command, the host MCU should wait 1 ms before sending in any new command. After that, the device goes to SLEEP state. The command is shown as Figure 23.

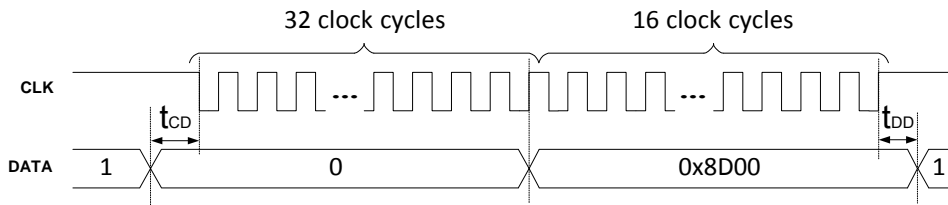


Figure 20. TWI_RST Command When Transmission Enabled by DATA Pin Falling Edge

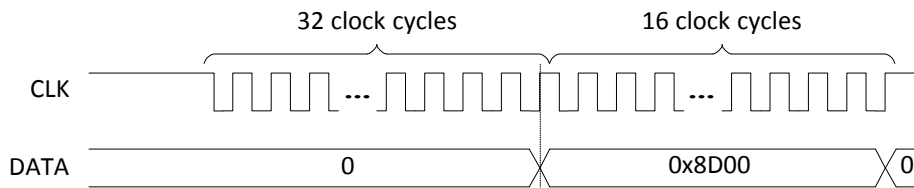


Figure 21. TWI_RST Command When Transmission Enabled by DATA Pin Rising Edge

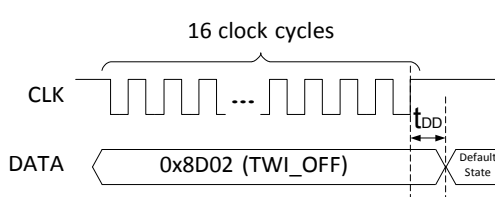


Figure 22. TWI_OFF Command

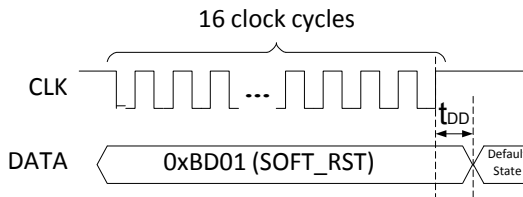


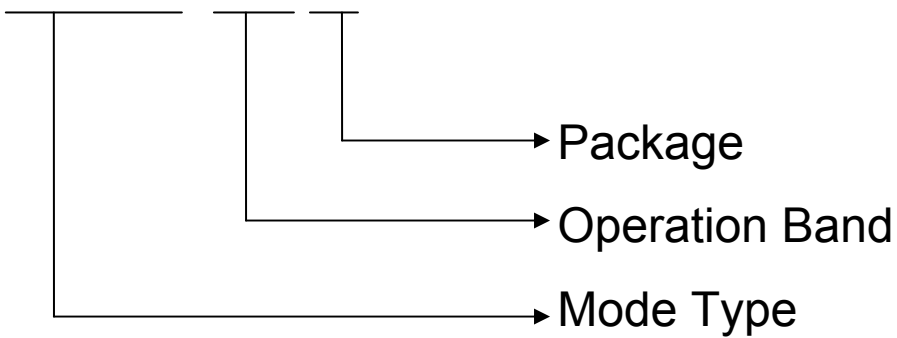
Figure 23. SOFT_RST Command

The DATA is generated by the host MCU on the rising edge of CLK, and is sampled by the device on the falling edge. The CLK should be pulled up by the host MCU during the TRANSMISSION shown in Figure 19. The TRANSMISSION process should refer to Figure 16 or Figure 17 for its timing requirement, depending on the “Start By” setting configured on the RFPDK.

The device will go to SLEEP state by driving the DATA low for t_{STOP} , or issuing SOFT_RST command. A helpful practice for the device to go to SLEEP is to issue TWI_RST and SOFT_RST commands right after the useful data is transmitted, instead of waiting the t_{STOP} , this can save power significantly.

6. Ordering Information

YTX119-433 S2



P/N: YTX119-315S2

YTX119 module at 315MHz band,SMD Package

P/N: YTX119S-433S2

YTX119S module at 433.92MHz band ,SMD Package

7. Package Outline

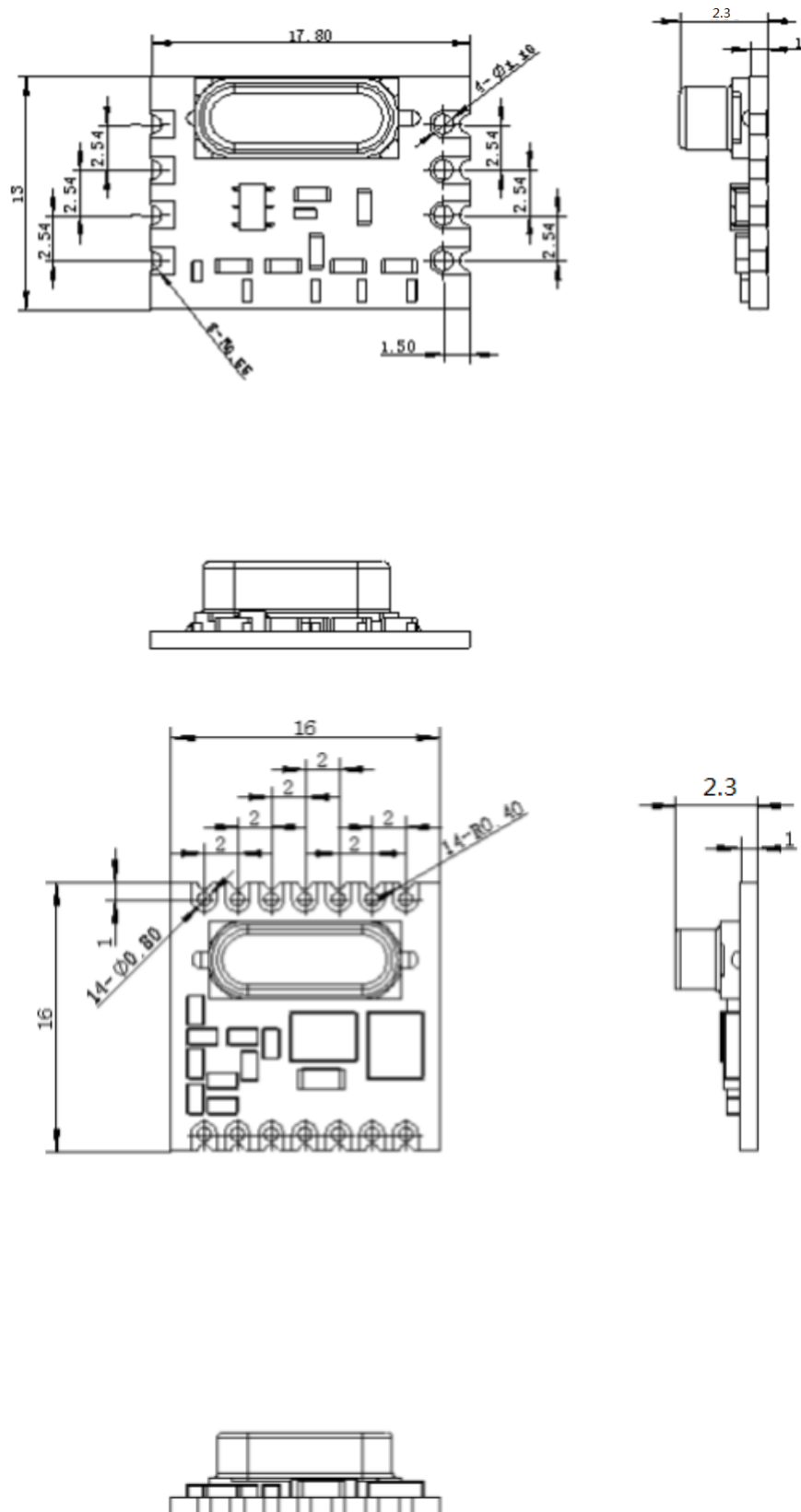


Figure 18 S1 Package Outline Drawing

